

**AMENDMENTS TO THE CLAIMS**

This listing of claims will replace all prior versions, and listings, of claims in the application.

**Listing of Claims:**

1. (Withdrawn) A dispenser system for a liquid crystal display panel, comprising:  
at least one table upon which a substrate having a plurality of image display parts is loaded;  
a plurality of syringes each having a nozzle at one end portion for supplying a dispensing material onto the substrate; and  
a plurality of robot arms having the plurality of syringes arranged at both sides of the table.
2. (Withdrawn) The system according to claim 1, wherein a plurality of thin film transistor array substrates are formed on the substrate.
3. (Withdrawn) The system according to claim 1, wherein a plurality of color filter substrates are formed on the substrate.
4. (Withdrawn) The system according to claim 1, wherein the plurality of image display parts include at least two groups each having different sizes.
5. (Withdrawn) The system according to claim 1, wherein the table is moved along horizontal forward/backward and left/right directions.
6. (Withdrawn) The system according to claim 1, wherein the dispensing material is a sealant material.
7. (Withdrawn) The system according to claim 1, wherein the dispensing material is a liquid crystal material.
8. (Withdrawn) The system according to claim 1, wherein the dispensing material is a silver material.

9. (Withdrawn) The system according to claim 1, wherein the image display parts have a matrix configuration.

10. (Canceled)

11. (Currently Amended) A dispensing method for a liquid crystal display panel, comprising:

mounting first, second and third pluralities of syringes each having a nozzle at one end portion at first, second and third pluralities of robot arms arranged at opposing sides of first, second and third tables, respectively, at least two robot arms arranged at each opposing side of the first, second and third tables,

wherein the first, second and third pluralities of robot arms convey the first, second and third pluralities of syringes to desired positions on the first, second and third tables;

loading a substrate having a plurality of image display parts onto the first table;

forming a first plurality of seal patterns along outer edges of a first plurality of image display parts by using the first plurality of syringes;

loading the substrate having the first plurality of seal patterns onto the second table;

forming a second plurality of seal patterns along outer edges of a second plurality of image display parts by using the second plurality of syringes;

loading the substrate having the first and second plurality of seal patterns onto the third table;

forming a third plurality of seal patterns along outer edges of a third plurality of image display parts by using the third plurality of syringes,

wherein the first plurality of image display parts each have a first size, the second plurality of image display parts each have a second size different from the first size and the third plurality of image display parts each have a third size different from the first and second sizes;  
and

independently driving the first, second and third tables along a convey path of supplying a dispensing material through the nozzles onto the substrate,

wherein driving the first, second and third tables includes moving the first, second and third tables along horizontal forward/backward and left/right directions to supply the dispensing

material onto predetermined locations of the substrate without moving the first, second and third pluralities of robot arms.

12. (Cancelled)

13. (Currently Amended) A dispensing method for a liquid crystal display panel, comprising:

mounting first and second pluralities of syringes each having a nozzle at one end portion at first and second pluralities of robot arms arranged at opposing sides of first and second tables, respectively, at least two robot arms arranged at each opposing side of the first and second tables;

loading a substrate having a first plurality of image display parts and a second plurality of image display parts onto the first table, wherein the first plurality of image display parts have a first size and the second plurality of image display parts have a second size;

forming a plurality of first seal patterns along outer edges of the first image display parts by using the first plurality of syringes;

loading the substrate having the first plurality of seal patterns onto the second table;

forming a second plurality of seal patterns along outer edges of the second plurality of image display parts by using the second plurality of syringes,

wherein the first plurality of image display parts each have a first size and the second plurality of image display parts each have a second size different from the first size; and

independently driving the first and second tables along a convey path of the substrate,

wherein driving the first and second tables includes moving the first and second tables along horizontal forward/backward and left/right directions to form the first and second plurality of seal patterns onto predetermined locations of the substrate without moving the first and second pluralities of robot arms.

14 - 19. (Cancelled)